UUVs in Battlespace Dominance

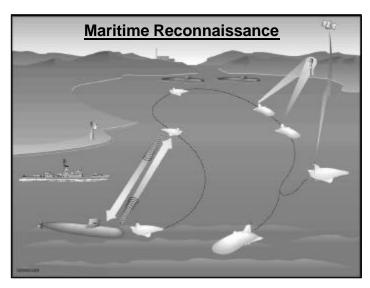


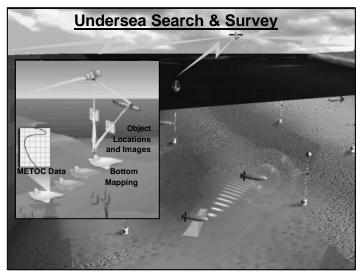
Dr. Douglas Todoroff
Organic MCM FNC Program Manager (ONR 32MIW)

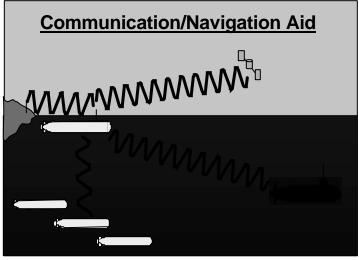
Voice: (703) 696-2485; Fax: (703) 696-2007; todorod@onr.navy.mil

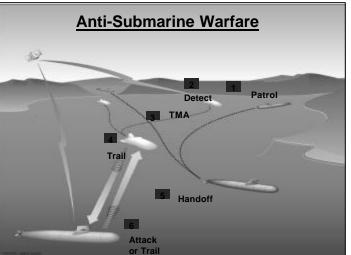


Some Key Applications

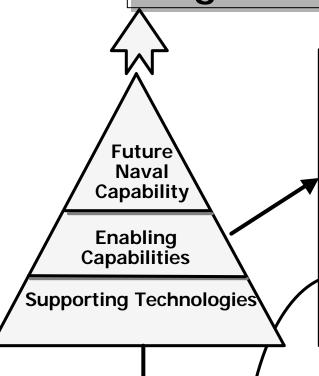








Organic Mine Countermeasures



- 1. Provide organic MCM...specifically in the very shallow water, surf zones, beach zones, craft landing zones, and beach exit zones (VSW/SZ/BZ/CLS/BEZ)...that enable operations in the littorals from the sea and STOM for all OMFTS capable craft.
- 2. Provide rapid, stand-off organic MCM capability to support maneuver of surface and subsurface combatants throughout the Littoral Penetration Area (LPA).
- 3. Provide rapidly deployable MCM capability for SLOC, Q-route, and port clearance to assure access to seabases, Intermediate Staging Bases and Sea Ports of Debarkation to ensure strategic mobility and sustainment.

List the principal supporting technologies

- Detection
 - Distributed Systems
 - Broadband sensing
 - Synthetic Aperture Sonar
 - LIDAR/Hyperspectral

- Remote/autonomous systems
 - UUVs, USVs, UGVs
- Mine /Obstacle Breaching
- Buried Mine Detection
- Data Fusion
- Common Tactical Picture

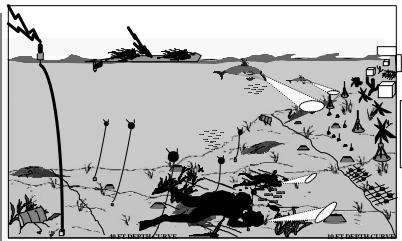


Clandestine Reconnaissance Capability Objective

- Rapid <u>Clandestine</u> Very Shallow Water / Surf Zone Minefield and Obstacle Reconnaissance

- Increase Margins of Safety for Diver
- Reduce Tactical Timelines
 - From Slow, Diver-Centered
 Operations to Multi-Tasked,
 UUV-Centered Area
 Operations
- Enables Maneuver Space Critical to STOM
 - From Narrow Linear Lanes
 - To Tactical Flexibility Along the Coast



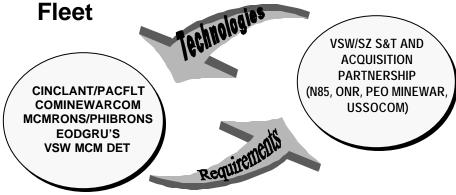






Ocean Engineering & Marine Systems System Development Strategy

 Connectivity Between R&D / Acquisition Communities and the



- Notional System Description
 - Easily Deployable, Low Cost Platforms
 - Recon, Reacquisition, Inspection, Marking
- Notional CONOPS
 - Wide Area Recon
 - Lane Recon
 - Lane Clearance

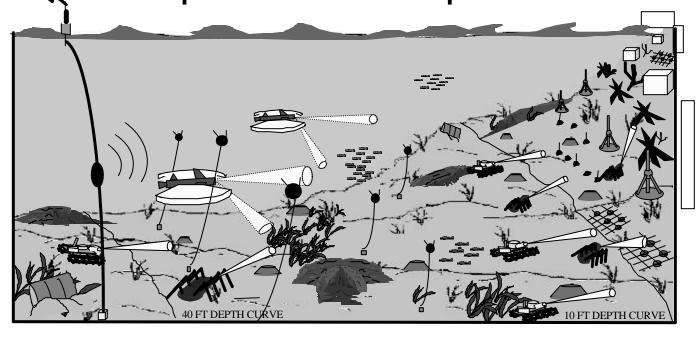
- Develop/Demonstrate Critical Component Technologies
 - Navigation
 - Communications
 - Sensors
 - Control
 - Employ Mature Platforms
- Interact with User
 - Show User
 - Learn from User
- Refine Concept of Operations
- Refine Notional System
- Demo Critical Elements of Ops
 - Fleet Battle Experiments
- Enable Low-Risk Smart Acquisition



Ocean Engineering & Marine Systems Capability Demonstrations



Multiple UUV Reconnaissance / Preparation of Area of Operations



KEY ELEMENTS OF DEMONSTRATIONS

- AUV Deployed Transponders
- Area Reconnaissance
- Data Relay to Command
- CAD / CAC Processing, Area of Ops Visualization, Computer-Aided Lane ID
- Command Redirection

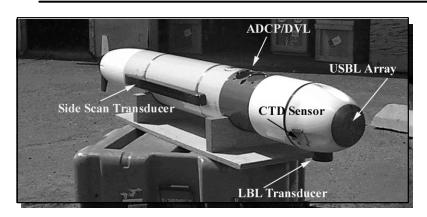
- Reacquisition and Inspection of Targets
- Placement of Target Markers and/or Neutralization Devices
- Placement of Lane Markers
- Command Actuation







Ocean Engineering & Marine Systems Test Bed & Demonstration Platforms



REMUS/WHOI

- Miniaturized DVL
- Multi-vehicle COMMS / NAV System
 CAD / CAC (CSS, LM, Raytheon)
- Payload Delivery
- Optical Imaging



Lemming / FMI / CSS

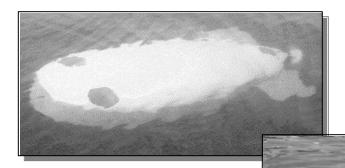
• PEIC

Tactile Sensors

• CCD

Sidescan Sonar (Marine Sonics)

OEX



CETUS / LM Perry

- Advanced FLS
- Low Light Video Imaging
- REMUS Reacquisition Package
- CETUS II





Modular AUV / FAU

- Multi-Vehicle Interoperability
- Mine Hunting Strategies
- 100 / 390 and 1200 KHz Side Scan Sonars
- Extensive / Modular Sensor Packages



SAHRV in Action





Operations within Kelp

Chemical Sensing in the Marine Environment





Millennium Challenge 2000



- ★ JFCOM/J9 Experimentation Directorate
- ★ Dates: August September 2000
- * "Collection of Experiments"
 - U.S. Army, JCF XXI
 - U.S Air Force, JEFX 00
 - USN, FBE-H
 - USMC, Millennium Dragon

★ Geographically Dispersed Locations

ascagoula Island eans



FBE-HOTEL



- **★ Objective:** Demonstrate emerging MCM technologies with **emphasis on UUVs**
- ★ Concept: Sailors and Marines:

-employ technologies, interpret products, provide feedback

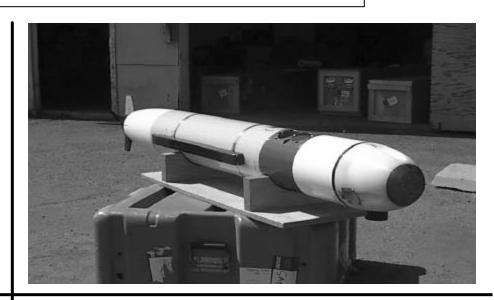
ONR POs and PIs:

-provide tech assist, collect & analyze data, continue S&T



VSW Mine Hunting

- * REMUS/SAHRV
- * CETUS II
- **★ MORPHEUS**







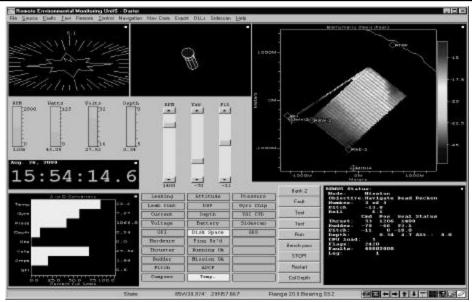


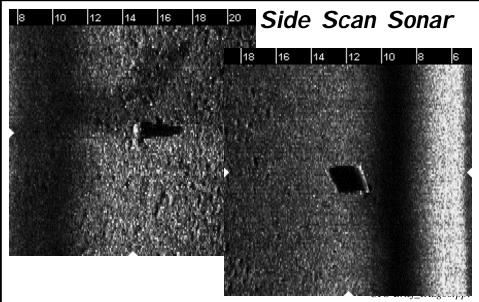
SEMI-AUTONOMOUS HYDROGRAPHIC RECONNAISSANCE VEHICLE







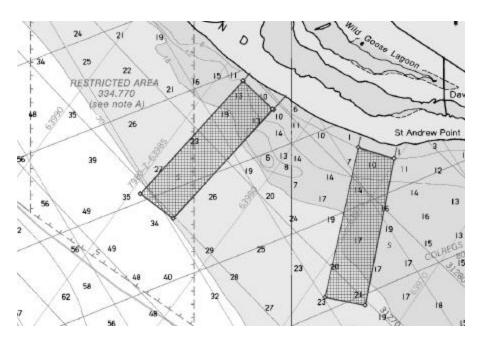






RED Beach Survey



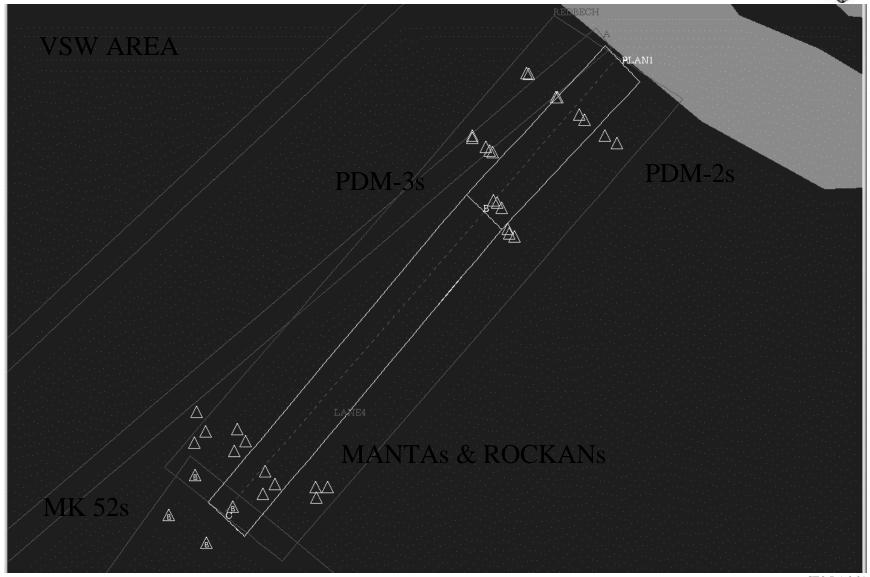


- •3400 Meter by 900 meter area (563 football fields)
- •3 Nights, 125 Kilometers, 65 nautical miles
- •100 percent bottom coverage
- •Data processed and turned over to MEDAL within hours of recovery



VSW Ground Truth

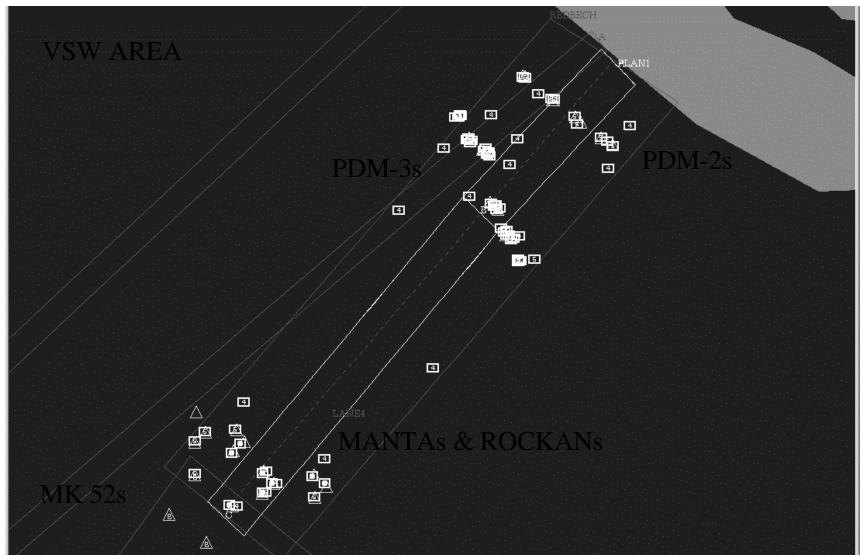






REMUS & Ground Truth

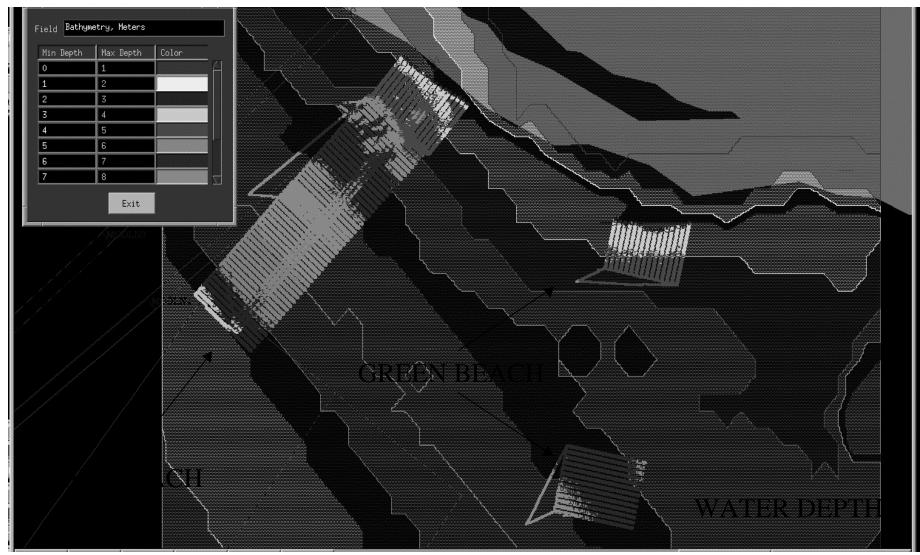






SAHRV vs NAVO







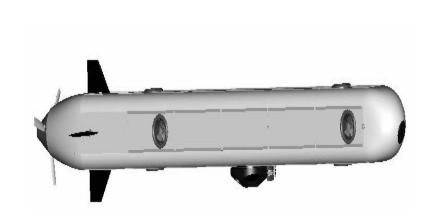
SAHRV/REMUS

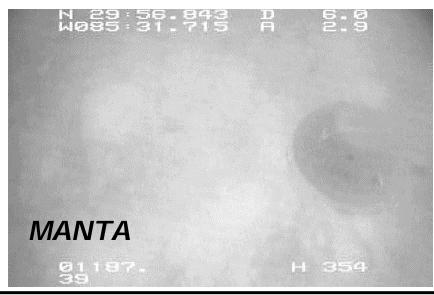


- ★ Employed by NAVSPECWARCOM and MCM VSW Det.
- ★ Conducted hydrographic recon and mine hunting in VSW
 - -51 CRN'S; P_c =97% (with a low P_{fa})
 - 32 hours on task (8 missions)
 - 2 Sq. NM coverage area (2 beaches)
- ★ Estimate six 2-man diver teams 48+ nights to minehunt the same area



MORPHEUS





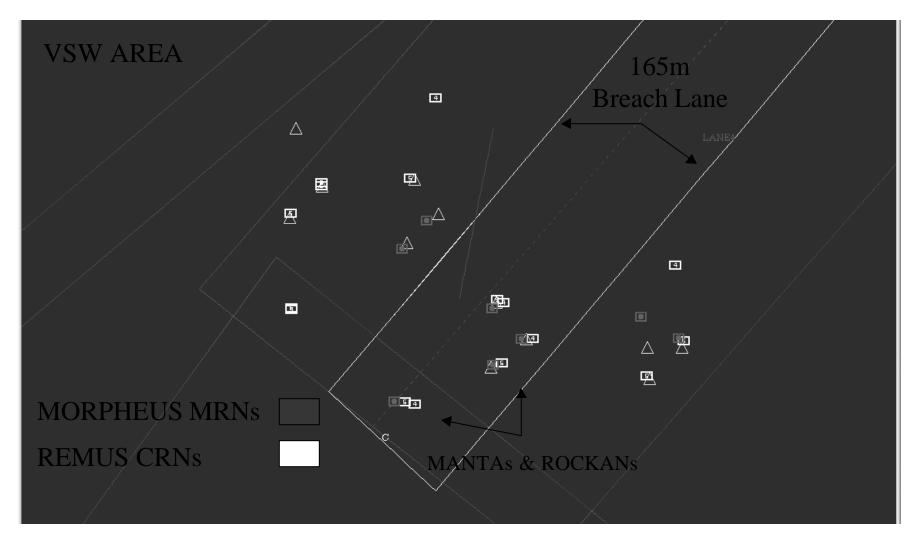






REMUS, MORPHEUS & Ground Truth







MORPHEUS



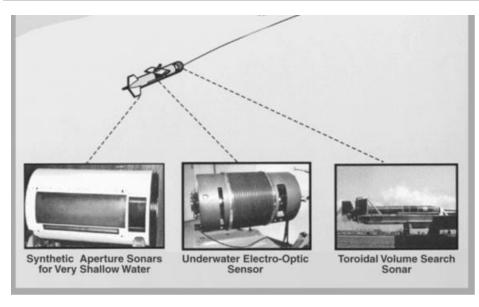
- ★ Reacquired and ID'd (video) 10 mines and 2 NOMBOs in the VSW and SW zones.
- ★ First time an AUV reacquired and ID'd an AUV acquired MLO.
- * PMA by USN EOD yields MRN' designation.
- ★ Video image snippets entered in CTP via MEDAL.
- ★ 5 missions: VSW through 75'.



Deep/SW Mine Hunting

- **★** Battlefield Planning AUV (BPAUV)
- * A/S--TVSS & SAS/EOID
- **★** OCEAN EXPLORER





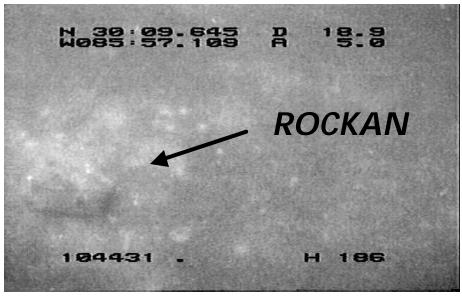


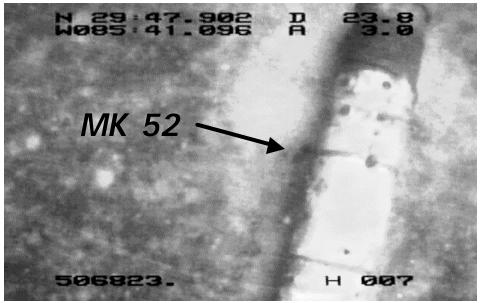


OCEAN EXPLORER





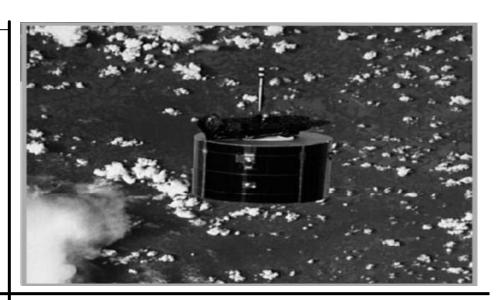






Surveillance & Reconnaissance

- ★ Littoral Remote Sensing (LRS)
- ★ Airborne Remote Optical Spotlighting System (AROSS)
- ★ Littoral Airborne Sensor-Hyperspectral (LASH)



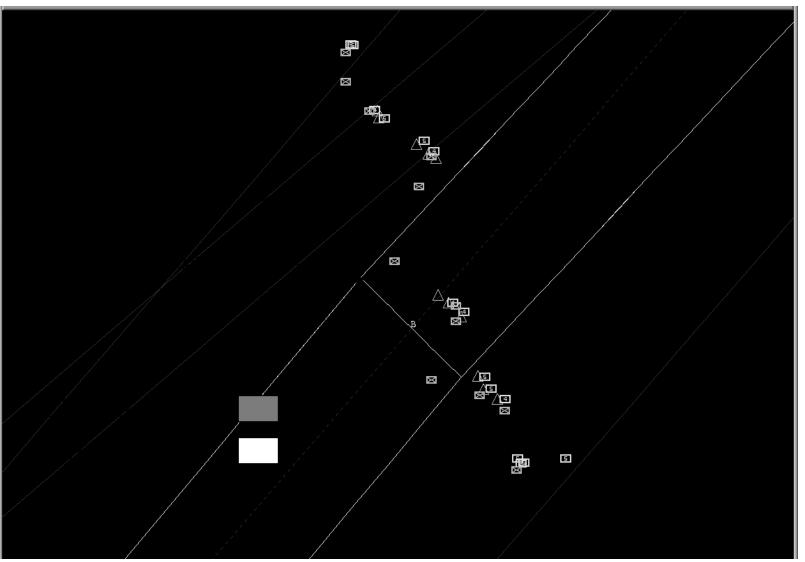






Ground Truth - LRS & AROSS

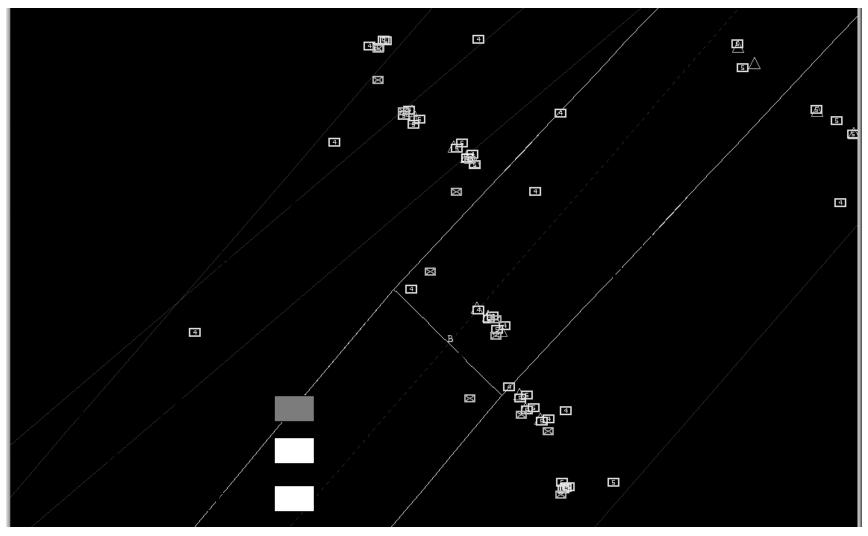






Ground Truth --LRS/AROSS/REMUS







Bottom Line

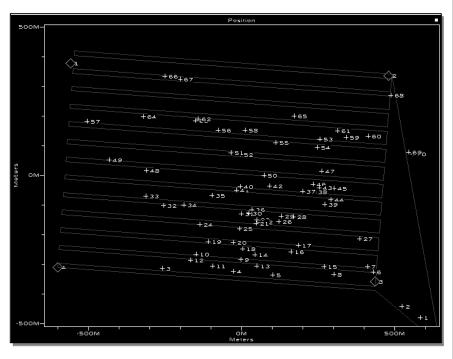


- ★ UUVs: Demonstrated the capability to "reduce the tactical timeline & get the diver/mammal out of the minefield"
 - Significant battlespace coverage
 - "Speedy" mission completion; timely info feedback
 - Accurate
 - LRS, AROSS & UUV data fusion led to 100% I D of PDM-3s
- **★** Favorable demonstration conditions
 - low sea state
 - A1 Bottom
 - Good acoustic conditions



VSW/SZ MCM Program

Effects of Coral Bottom on Mine Detection



- Very Difficult Bottom for MCM Operations Bottom Type B3
- Large False Contact Rate
- 74 Contacts Called
- 14 Actual Targets in Area

CAD/CAC

SAHRV Field Evaluation II Sep 98 562 sonar images, 80 mines (area = 670m by 670m)

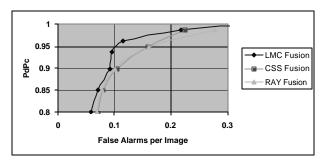
STANDALONE CAD / CAC RESULTS

		False Alarms Per
Algorithm	PdPc	Image
CSS	93.8 (75 / 80)	0.365 (205 / 562)
RAY	90.0 (72 / 80)	1.240 (697 / 562)
LMC	96.3 (77 / 80)	2.039 (1146 / 562)

FUSION OF CSS, RAY, & LMC CAD / CAC OUTPUTS

	False Alarms in 562 Images				
PdPc (%)	CSS (1)	RAY (2)	LMC (3)		
98.8 (79 / 80)	126	156	123		
95.0 (76 / 80)	90	91	60		
90.0 (72 / 80)	59	57	52		
85.0 (68 / 80)	45	44	40		
80.0 (64 / 80)	40	39	33		

- (1) CSS Fusion: METHOD BASED ON MAXIMIZING FISHER RATIO
- (2) RAY Fusion: OPTIMIZED THREE-TEAM OR-ING
- (3) LMC Fusion: ORTHOGONAL LLRT





OEX AUV - 13 June 00 - Manta AA002 Acoustically Transmitted Image



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N 26:04.423 D
W080:05.350 A
284558
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Ocean Engineering and Marine Systems 1st Generation Small MCM UUVs: Acquisition



PMS - EOD Acquisition

NOTIONAL S-C-M SYSTEM (1ST GEN)

- 4 SWIMMERS
- 2 NAV SETS
- 1 C2/TDA SYSTEM SUPPORT EQUIPMENT

NOTIONAL R-I-N SYSTEM (1ST GEN)

- **6 VEHICLES**
- 2 NAV SETS
- 1 C2/TDA SYSTEM SUPPORT EQUIPMENT

QUANTITIES	00	01	02	03	04	05	TOTAL
VSW MCM	AOA				2*	6	S-C-M
DET	,	AOA				1*	R-I-N
BG/ARG EOD						0	S-C-M
DETs						1*	R-I-N

PMS - 325J (USSOCOM) SAHRV Acquisition: IOC 02





UUVs for Battlespace Dominance

- Key ONR Program Managers
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 - sweant@onr.navy.mil
 - Dr. Tom Curtin (AO FNC UUVs)
 - curtint@onr.navy.mil

UUVs in Battlespace Dominance



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